STAT 946 - Topics in Probability and Statistics: Mathematical Foundations of Deep Learning Lecture 7

Lucas Noritomi-Hartwig University of Waterloo

September 24, 2025 from 16h00 to 17h20 in M3 3103

October 6th: Majid (Deep RL), Marty (MF Transformers) presenting articles.

October 20th: ??

October 8th: Last day to decide on a topic and direction for a project.

Recall

$$f(x^{\alpha}; \theta) = \frac{1}{\sqrt{n}} W_d \varphi(h_d)$$
$$h_{l+1}^{\alpha} = \frac{1}{\sqrt{n}} W_l \varphi(h_l)$$
$$h_1^{\alpha} = \frac{1}{\sqrt{n_0}} W_0 x^{\alpha}$$

Backward neuron:

$$\begin{split} g_{l}^{\alpha} &= \sqrt{n} \frac{\partial f^{\alpha}}{\partial h_{l}^{\alpha}} \\ z_{l}^{\alpha} &= \frac{1}{\sqrt{n}} W_{l}^{\top} g_{l+1}^{\alpha} \\ &= \frac{1}{\sqrt{n}} W_{l}^{\top} \underbrace{\operatorname{diag} \left(\varphi' \left(h_{l+1}^{\alpha} \right) \right)}_{=: D_{l+1}^{\alpha}} z_{l+1}^{\alpha} \\ \mathcal{F}_{l}^{z} &= \sigma \left(\left\{ h_{k}^{\alpha} \right\}_{\alpha, k}, \left\{ z_{k} \right\}_{k > l} \right) \end{split}$$

$$W|\sigma\left(W\varphi\right) \stackrel{\mathrm{d}}{=} WP_{\varphi} + \underbrace{\tilde{W}}_{\text{indep. copy}} P_{\varphi}^{\perp}$$

$$z_{l}^{\alpha}|\mathcal{F}_{l}^{z} = \frac{1}{\sqrt{n}} \left(P_{\varphi_{l}}W_{l}^{\top} + P_{\varphi_{l}}^{\perp}\tilde{W}_{l}^{\top}\right) D_{l+1}^{\alpha} z_{l+1}^{\alpha}|\mathcal{F}_{l}^{z}$$

$$= P_{\varphi_{l}} z_{l}^{\alpha} + P_{\varphi_{l}}^{\perp} \underbrace{\frac{1}{\sqrt{n}} \tilde{W}_{l}^{\top} g_{l+1}^{\alpha}}_{\tilde{z}_{l}^{\alpha} \sim \mathcal{N}(0, G_{l+1} \otimes I)} |\mathcal{F}_{l}^{z}| \qquad (h_{l+1} = W_{l}\varphi\left(h_{l}\right))$$

$$G_{l}^{\alpha\beta} = \frac{1}{n} \left\langle g_{l}^{\alpha}, g_{l}^{\beta} \right\rangle$$

$$= \frac{1}{n} \left\langle D_{l}^{\alpha} z_{l}^{\alpha}, D_{l}^{\beta} z_{l}^{\beta} \right\rangle$$

$$= \frac{1}{n} \left\langle D_{l}^{\alpha} \left(P_{\varphi_{l}} z_{l}^{\alpha} + P_{\varphi_{l}}^{\perp} \tilde{z}_{l}^{\alpha} \right), D_{l}^{\beta} \left(P_{\varphi_{l}} z_{l}^{\beta} + P_{\varphi_{l}}^{\perp} \tilde{z}_{l}^{\beta} \right) \right\rangle$$

$$= \frac{1}{n} \left\langle D_{l}^{\alpha} P_{\varphi_{l}} z_{l}^{\alpha}, D_{l}^{\beta} P_{\varphi_{l}} z_{l}^{\beta} \right\rangle$$

$$= \frac{1}{n} \left\langle D_{l}^{\alpha} P_{\varphi_{l}} z_{l}^{\alpha}, D_{l}^{\beta} P_{\varphi_{l}} z_{l}^{\beta} \right\rangle$$

$$(1)$$

$$+\frac{1}{n}\left\langle D_l^{\alpha} P_{\varphi_l}^{\perp} \tilde{z}_l^{\alpha}, D_l^{\beta} P_{\varphi_l} z_l^{\beta} \right\rangle \tag{2}$$

$$+\frac{1}{n}\left\langle D_l^{\alpha} P_{\varphi_l} z_l^{\alpha}, D_l^{\beta} P_{\varphi_l}^{\perp} \tilde{z}_l^{\beta} \right\rangle \tag{3}$$

$$+\frac{1}{n}\left\langle D_l^{\alpha} P_{\varphi_l}^{\perp} \tilde{z}_l^{\alpha}, D_l^{\beta} P_{\varphi_l}^{\perp} \tilde{z}_l^{\beta} \right\rangle \tag{4}$$

$$(1) = \frac{1}{n} \sum_{j=1}^{n} \underbrace{\varphi'\left(h_{l,j}^{\alpha}\right)}_{\in\Theta(1)} \left(P_{\varphi_{l}} z_{l}^{\alpha}\right)_{j}$$

 $\|P_{\varphi_l}z_l^{\alpha}\|^2$ is a projection on the column space of φ_l , namely $\operatorname{col}(\varphi_l)$, where φ_l is $n \times m$.

$$\varphi_l = \left[\varphi \left(\underbrace{h_l^{(1)}}_{n \times 1} \right) \quad \varphi \left(\underbrace{h_l^{(2)}}_{n \times 1} \right) \quad \dots \quad \varphi \left(\underbrace{h_l^{(m)}}_{n \times 1} \right) \right]$$

In the trivial case, i.e., m = 1,

$$\varphi_l = e_1 = \begin{bmatrix} 1\\0\\\vdots\\0 \end{bmatrix} \in \mathbb{R}^n$$

$$P_{\varphi_l} z_l^{\alpha} = \begin{bmatrix} z_{l,1}^{\alpha}\\0\\\vdots\\0 \end{bmatrix}$$

So as $n \to \infty$, $||P_{\varphi_l} z_l^{\alpha}||^2 \lesssim \frac{m}{n} ||z_l^{\alpha}||^2$

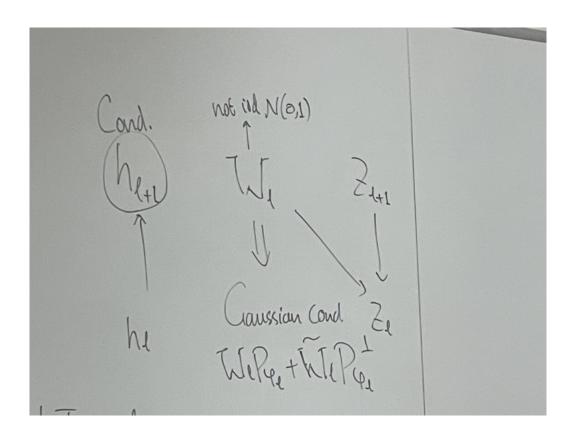
$$(2) + (3) = \frac{1}{n} \sum_{i} \cdots \left(\underbrace{P_{\varphi_{l}}^{\perp} \tilde{z}_{l}^{\alpha}}_{\text{zero mean, indep.}} \right)_{i} \cdots$$

$$\tilde{z}_{l}^{\alpha} = \frac{1}{\sqrt{n}} \underbrace{\tilde{W}_{l}^{\top}}_{\text{indep. copy of } W_{l}^{\top}} g_{l+1}^{\alpha}$$

$$(\dagger) = \frac{1}{\sqrt{n}} \Theta(1) \to \text{CLT scaling}$$

$$\to 0$$

$$(\dagger)$$



$$(4) = \frac{1}{n} \sum_{i=1}^{n} \varphi'\left(h_{l,i}^{\alpha}\right) \tilde{Z}_{l,i}^{\alpha} \varphi'\left(h_{l,i}^{\beta}\right) \tilde{z}_{l,i}^{\beta} - \cdots \underbrace{\left(P_{\varphi_{l}} \tilde{z}_{l}^{\alpha}\right)}_{\Theta(m \ n) \to 0} \cdots \left(P_{\varphi_{l}} \tilde{z}_{l,i}^{\beta}\right)$$

$$\to \mathbb{E} \left[\varphi'\left(h_{l,i}^{\alpha}\right) \varphi'\left(h_{l,i}^{\beta}\right) \mathbb{E} \left[\underbrace{\tilde{z}_{l,i}^{\alpha} \tilde{z}_{l,i}^{\beta}}_{\to G_{l+1}^{\alpha\beta}} | \mathcal{F}_{l+1}^{z} \right] \right]$$

$$P_{\varphi_{l}}^{\perp} \tilde{z}_{l}^{\alpha} = P_{\varphi_{l}}^{\perp} \frac{1}{\sqrt{n}} \tilde{W}_{l}^{\top} g_{l+1}^{\alpha} \sim \mathcal{N} \left(0, G_{l+1}^{\alpha\beta} \otimes \underbrace{P_{\varphi_{l}}^{\perp}}_{=I - P_{\varphi_{l}}} \right)$$

Aside:

$$\sum_{i=1}^{n} X_i \to X \implies \sum_{i=1, i \neq 2}^{n} X_i \to X,$$

i.e., finitely many random varibales contribute infinitesimally small amounts to the limit.

$$\begin{split} \dot{\Phi}_{l}^{\alpha\beta} := \mathbb{E}\left[\varphi'\left(h_{l,\,i}^{\alpha}\right)\varphi'\left(h_{l,\,i}^{\beta}\right)\right] \\ G_{l}^{\alpha\beta} = \dot{\Phi}_{l}^{\alpha\beta}\odot G_{l+1}^{\alpha\beta} \end{split}$$

where $A \odot B = \left[a_{ij}b_{ij}\right]_{ij}$ is the Hadamard product of A and B.

NTK:

$$K^{\alpha\beta} = \sum_{l=0}^{d} \left\langle \nabla_{W_{l}} f^{\alpha}, \nabla_{W_{l}} f^{\beta} \right\rangle$$

$$\sum_{l=0}^{d} \frac{1}{n} \left\langle g_{l+1}^{\alpha}, g_{l+1}^{\beta} \right\rangle \frac{1}{n} \left\langle \varphi_{l}^{\alpha}, \varphi_{l}^{\beta} \right\rangle$$

$$= \sum_{l=0}^{d} G_{l+1}^{\alpha\beta} \Phi_{l}^{\alpha\beta}$$

$$\Phi_{l}$$

$$\Phi_{l}$$

$$\Phi_{l}$$

$$\Phi_{l}$$

$$\Phi_{l}$$

$$\Phi_{l}$$

Theorem

$$\begin{cases} \Phi_{l+1} = f_1 \left(\Phi_l \right) \\ G_l = \dot{\Phi}_l \odot G_{l+1} \\ \Phi_0 = \left[\frac{1}{n_0} \left\langle x^{\alpha}, x^{\beta} \right\rangle \right]_{\alpha, \beta} \\ G_{d+1} = 11^{\top} \end{cases}$$

$$K = \sum_{l=0}^{d} \Phi_l \odot G_{l+1}$$

$$\dot{\Phi}_{l+1} = f_2 \left(\Phi_l \right)$$

$$\dot{\Phi}_{l+1} = \mathbb{E} \left[\varphi' \left(h^{\alpha} \right) \varphi' \left(h^{\beta} \right) \right]$$

$$\begin{bmatrix} h^{\alpha}_{h} \\ h^{\beta} \end{bmatrix} \sim \mathcal{N} \left(0, \begin{bmatrix} \Phi_l^{\alpha \alpha} & \Phi_l^{\alpha \beta} \\ \Phi_l^{\beta \alpha} & \Phi_l^{\beta \beta} \end{bmatrix} \right)$$

$$z_l^{\alpha} = P_{\varphi_l} z_l^{\alpha} + P_{\varphi_l}^{\perp} \tilde{z}_l^{\alpha} \end{cases}$$

Generalization

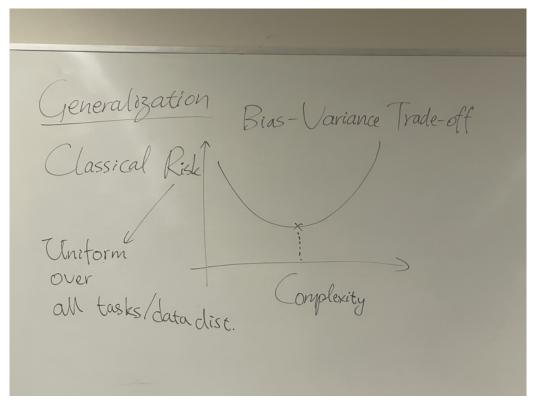
Something of which we have a completely new understanding since 2018-2019.

Classical view: bias-variance tradeoff, i.e., in order to perform better (have low risk), we must regularize our model's complexity.

What is risk? In classical theories, "risk" is defined in a very restrictive way.

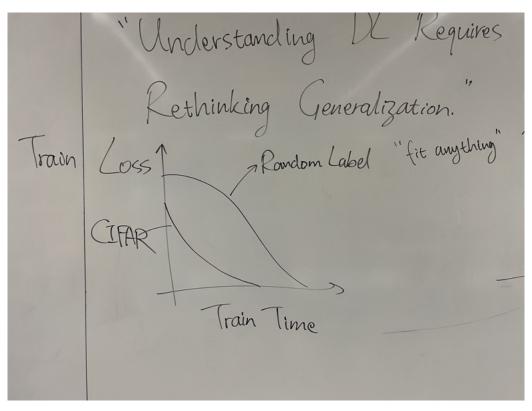
No Free Lunch Theorem

Informally: If algorithm A can fit any data, then \exists a task (data distribution) on which A fails, i.e., there is some fixed amount of risk under which A cannot output a model that performs better than the risk.

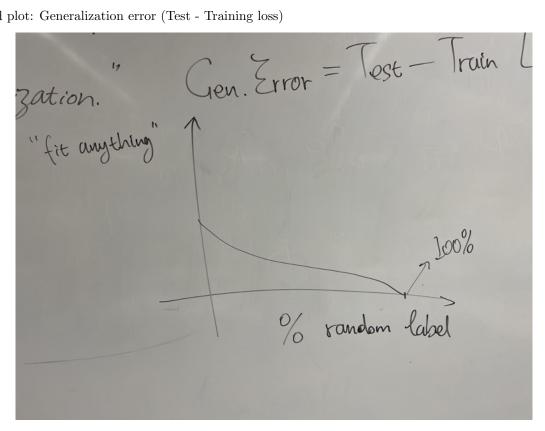


"Understanding Deep Learning Requires Rethinking Generalization" - Zhang et al (2016)

First plot: Training loss



Second plot: Generalization error (Test - Training loss)



Belkin et al. (2018) "Double Descent"

