Stat 946 - Topics in Probability and Statistics: Mathematical Foundations of Deep Learning $Lecture\ 5$

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1 NTK for network with 1 Hidden Layer of width n

Recap: The network function $f(\cdot; \theta)$ is parameterized by the weights $\theta = \{\underbrace{W_0}_{n \times n_0}, \underbrace{W_1}_{1 \times n}\}$ where $W_{l,ij}$ are i.i.d. realizations of N(0,1).

The network's output f^{α} for input $\underbrace{x^{\alpha}}_{n_0 \times 1}$ is defined as follows:

$$f^{\alpha} = (1/\sqrt{n}) \cdot W_1 \cdot \psi(h_1^{\alpha})$$

where $\underbrace{h_1^{\alpha}}_{n\times 1} = W_0 \cdot x^{\alpha}$ refers to the corresponding hidden layer for input x^{α} and ψ is an activation function applied to each component in the column input individually.

The network function f is trained on a data-set, \mathcal{D} , of size m:

$$\mathcal{D} = \{(x^{\alpha}, y^{\alpha})\}_{\alpha=1}^{m}$$

and the loss observed by the network f as a function of the parameters θ is specified below:

$$\mathcal{L}(\theta) = (1/(2 \cdot m)) \cdot \Sigma_{\alpha=1}^{m} (f^{\alpha} - y^{\alpha})^{2}$$

An application of chain rule allows us to model the gradient flow (i.e. $\underbrace{\partial_t}_{\partial/\partial_t=d/d_t}\theta(t)$) using the following differential equation:

$$\begin{aligned} \partial_t \theta(t) &= -\nabla_\theta \mathcal{L}(\theta(t)) \\ &= -(1/m) \cdot \Sigma_{\alpha=1}^m (f^\alpha - y^\alpha) \cdot \nabla_\theta f^\alpha \end{aligned} \tag{1}$$

We can write out the change in the residual, $\partial_t(f^{\alpha} - y^{\alpha})$, for input x^{α} as follows:

$$\partial_{t}(f^{\alpha} - y^{\alpha}) = \partial_{t}f^{\alpha}
= \langle \nabla_{\theta}f^{\alpha}, \partial_{t}\theta(t) \rangle
= -(1/m) \cdot \Sigma_{\beta=1}^{m} \underbrace{\langle \nabla_{\theta}f^{\alpha}, \nabla_{\theta}f^{\beta} \rangle}_{\mathcal{K}_{t}^{n}(x^{\alpha}, x^{\beta})} \cdot (f^{\beta} - y^{\beta})$$
(2)

The second equality is another application of the chain-rule. The last equality is obtained by substituting $theta_t$ into $\partial_t \theta(t)$. The random tangent Kernel, $\mathcal{K}_t^n(\cdot;\cdot)$, which is implicitly parameterized by θ is also referred to as the NTK. Note that $\partial_t (f^{\alpha} - y^{\alpha})$ can be viewed as a mixture of the rest of the residuals (i.e. $\{f^{\beta} - y^{\beta}\}_{\beta=1,\dots,m}$).

Jacot et al. (2020) prove the following:

Theorem 1. In the infinite-width limit (i.e $n \to \infty$), by the law of large numbers (LLN), the random tangent kernel, K_t^n , tends to a deterministic kernel, $\mathcal{K} = [\mathcal{K}(x^{\alpha}, x^{\beta})]_{\alpha, \beta=1}^m$, which stays constant during the entire training process.

Now we can apply Theorem 1 and rewrite the change in the residuals, Eq. (2), using the following linear DE:

$$\partial_t \underbrace{(f-y)}_{m \times 1} = -(1/m) \cdot \underbrace{\mathcal{K}}_{m \times m} \cdot (f-y) \tag{3}$$

We can view $(1/m) \cdot \mathcal{K}$ as the *pre-conditioner* on the *co-ordinate* (f - y).

The differential equation expressed as Eq. (3) has the following solution:

$$(f - y) = \exp\{-(1/m) \cdot \mathcal{K} \cdot t\} \cdot (f(\theta(0)) - y) \tag{4}$$

where the exponential operation on a matrix A refers to:

$$\exp\{A\} = \mathcal{I} + A + A^2/2! + A^3/3! + \cdots$$

Let's generalize the loss function on our training set of size m:

$$\mathcal{L}^*(\theta) = (1/m) \cdot \Sigma_{\alpha=1}^m l(f^{\alpha}, x^{\alpha})$$

Now we can model the evolution of the generalized loss function using the following differential equation:

$$\partial_{t}\mathcal{L}^{*}(\theta(t)) = (1/m) \cdot \Sigma_{\alpha=1}^{m} \partial_{f^{\alpha}} l(f^{\alpha}, y^{\alpha}) \cdot \partial_{t} f^{\alpha}$$

$$= (-1/m^{2}) \cdot \Sigma_{\alpha=1}^{m} \partial_{f^{\alpha}} l(f^{\alpha}, y^{\alpha}) \cdot \Sigma_{\beta=1}^{m} \mathcal{K}(x^{\alpha}, y^{\beta}) \cdot \partial_{f^{\beta}} l(f^{\beta}, y^{\beta})$$

$$= (-1/m^{2}) \cdot (\partial_{x} l(f, y))^{T} \cdot \mathcal{K} \cdot \partial_{x} l(f, y)$$
(5)

where $\partial_x l(f, y)$ is an $m \times 1$ column-vector whose i^{th} entry refers to $\partial_{f^i} l(f^i, y^i)$ and the second equality is an exercise for the reader.

Let's revisit our original loss function $\mathcal{L}(\theta) = (1/(2 \cdot m)) \cdot ||f - y||^2$. We can apply similar logic as above to arrive at the following expression:

$$\partial_t \mathcal{L}(\theta(t)) = -(1/m^2) \cdot (f - y)^T \cdot \mathcal{K} \cdot (f - y)$$

Now we state the following lemma:

Lemma 2. Let $M \in \mathbb{R}^{m \times m}$ be a symmetric and PSD matrix. Let $\lambda^*(M)$ refer to the minimum eigenvalue of matrix M. For any $\mu \in \mathbb{R}^m$, $\lambda^*(M) \cdot ||u||^2 \leq u^T \cdot M \cdot u$.

Proof.

$$\begin{split} u^t \cdot M \cdot u &= u^T \cdot P \cdot D \cdot P^T \cdot u \\ &\geq \lambda^*(M) \cdot u^T \cdot P \cdot P^T \cdot u \\ &= \lambda^*(M) \cdot ||u||^2 \end{split}$$

The first inequality makes use of the non-negativity of the eigenvalues of the matrix and the last equality makes use of the orthogonal diagonalizability of symmetric matrices.

Now we can apply Lemma 2 with respect to our PSD kernel matrix K to derive the following differential inequality:

$$\begin{aligned} \partial_t \mathcal{L}(\theta(t)) &\leq -(\lambda^*(\mathcal{K}))/m^2) \cdot ||f - y||^2 \\ &= -(\lambda^*(\mathcal{K}))/m^2) \cdot 2 \cdot m \cdot \mathcal{L}(\theta(t)) \\ &= -2 \cdot (\lambda^*(\mathcal{K})/m) \cdot \mathcal{L}(\theta(t)) \\ &\leq -(1/2) \cdot (\lambda^*(\mathcal{K})/m) \cdot \mathcal{L}(\theta(t)) \end{aligned}$$

We apply *Grönwall's Inequality*, to get the following solution to the above differential inequality:

$$\mathcal{L}(\theta(t)) \le \exp\{-\frac{\lambda^*(\mathcal{K}) \cdot t}{2 \cdot m}\} \cdot \mathcal{L}(\theta(0)) \tag{6}$$

A consequence of Eq. (6) is that if $\lambda^*(\mathcal{K}) > 0$, then NN training should converge! Note that we can show that $\lambda^*(\mathcal{K}) > 0$ using RMT.

Exercises

Show the following chain of equalities:

1.

$$\begin{split} \mathcal{K}^n_t(\boldsymbol{x}^{\alpha}, \boldsymbol{x}^{\beta}) &= (1/n) \cdot \underbrace{\langle \psi(h_1^{\alpha}), \psi(h_1^{\beta}) \rangle}_{\text{GP Kernel } \psi(\boldsymbol{x}^{\alpha}, \boldsymbol{x}^{\beta})} \\ &+ (1/n) \cdot \langle \operatorname{diag}(\underbrace{\psi'(h_1^{\alpha})}_{n \times n}) \cdot \underbrace{(\underbrace{\boldsymbol{x}_{\alpha} \cdot \boldsymbol{W}_1}_{n \times n_0})^T}, \operatorname{diag}(\psi'(h_1^{\beta})) \cdot (\boldsymbol{x}_{\beta} \cdot \boldsymbol{W}_1)^T \rangle \end{split}$$

2.

$$\partial_t (\mathcal{K}_t^n(x^{\alpha}, x^{\beta})) = -(1/m) \cdot \Sigma_{\gamma=1}^m (f^{\alpha} - y^{\alpha}) \cdot \\ [(\nabla_{\theta} (f^{\beta}))^T \cdot \nabla_{\theta}^2 (f^{\alpha}) \cdot \nabla_{\theta} (f^{\gamma}) + (\nabla_{\theta} (f^{\alpha}))^T \cdot \nabla_{\theta}^2 (f^{\beta}) \cdot \nabla_{\theta} (f^{\gamma})]$$

3.

$$\begin{split} (\nabla_{\theta}(f^{\beta}))^T \cdot \nabla_{\theta}^2(f^{\alpha}) \cdot \nabla_{\theta}(f^{\gamma}) &= (\langle x^{\alpha}, x^{\beta} \rangle / \sqrt{n}) \cdot (1/n) \cdot \Sigma_{i=1}^n W_{1,i} \cdot \psi(h_{1,i}^{\beta}) \cdot \psi'(h_{1,i}^{\alpha}) \cdot \psi'(h_{1,i}^{\gamma}) \\ &\quad + (\langle x^{\alpha}, x^{\beta} \rangle / \sqrt{n}) \cdot (1/n) \cdot \Sigma_{i=1}^n W_{1,i} \cdot \psi(h_{1,i}^{\gamma}) \cdot \psi'(h_{1,i}^{\alpha}) \cdot \psi'(h_{1,i}^{\beta}) \\ &\quad + (\langle x^{\alpha}, x^{\beta} \rangle \cdot \langle x^{\alpha}, x^{\beta} \rangle / \sqrt{n}) \cdot \underbrace{(1/n) \cdot \Sigma_{i=1}^n W_{1,i}^3 \cdot \psi'(h_i^{\beta}) \cdot \psi''(h_i^{\alpha}) \cdot \psi'(h_i^{\gamma})}_{O(1)} \end{split}$$

A consequence of the above equalities is that $\partial_t(\mathcal{K}^n_t(x^\alpha, x^\beta)) = O(1/\sqrt{n}) \to 0$. Hence, the limiting kernel \mathcal{K}_t is also stationary (i.e. $\mathcal{K}_t = \mathcal{K}$) in the infinite-width limit.

2 References

Jacot, A., Gabriel, F., and Hongler, C. (2020). Neural tangent kernel: Convergence and generalization in neural networks.